# A meta-analysis of robotic vs. conventional mitral valve surgery

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**Objectives:** The present study is the first meta-analysis to compare the surgical outcomes of robotic *vs*. conventional mitral valve surgery in patients with degenerative mitral valve disease.

**Methods:** A systematic review of the literature was conducted to identify all relevant studies with comparative data on robotic *vs.* conventional mitral valve surgery. Predefined primary endpoints included mortality, stroke and reoperation for bleeding. Secondary endpoints included cross-clamp time, cardiopulmonary bypass time, length of hospitalization and duration of intensive care unit (ICU) stay. Echocardiographic outcomes were assessed when possible.

**Results:** Six relevant retrospective studies with comparative data for robotic vs. conventional mitral valve surgery were identified from the existing literature. Meta-analysis demonstrated a superior perioperative survival outcome for patients who underwent robotic surgery. Incidences of stroke and reoperation were not statistically different between the two treatment arms. Patients who underwent robotic surgery required a significantly longer period of cardiopulmonary bypass time and cross-clamp time. However, the lengths of hospitalization and ICU stay were not significantly different. Both surgical techniques appeared to achieve satisfactory echocardiographic outcomes in the majority of patients.

**Conclusions:** Current evidence on comparative outcomes of robotic *vs.* conventional mitral surgery is limited, and results of the present meta-analysis should be interpreted with caution due to differing patient characteristics. However, it has been demonstrated that robotic mitral valve surgery can be safely performed by expert surgeons for selected patients. A successful robotic program is dependent on a specially trained team and a sufficient volume of referrals to attain and maintain safety.

Keywords: Mini-mitral; robotic surgery; meta-analysis; mitral valve

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# Introduction

Over the past few decades, minimally invasive surgery has transformed the landscape of cardiothoracic surgery in a wide range of procedures (1-3). Mitral valve surgery has traditionally been performed through a conventional sternotomy approach. However, a number of studies have demonstrated that comparable repair techniques can be performed in selected patients through a minimally invasive right mini-thoracotomy approach with potentially superior perioperative outcomes (4,5). More recently, robotic surgery involving telemanipulation systems has been developed to enable surgeons to perform mitral valve surgery with increased degrees of movement and improved vision.

Despite technological improvements in miniature instrumentation and development of operative techniques through increased experience, the extent of benefits derived from robotic surgery in patients with mitral valve disease remains uncertain. Currently, robotic mitral valve surgery remains limited to specialized centers for patients with isolated mitral valve pathology. To systematically appraise the available evidence, the present study aimed to identify all relevant studies on mitral valve surgery to compare the outcomes of robotic *vs.* conventional approaches. Primary endpoints included mortality, stroke and re-operation for bleeding. Secondary endpoints included length of hospitalization, duration of intensive care unit (ICU) stay, cross-clamp time and cardiopulmonary bypass time. Echocardiographic outcomes before and after robotic or conventional surgery were also assessed. This study represents the first meta-analysis of robotic *vs.* conventional mitral valve surgery.

# Methods

# Literature search strategy

Electronic searches were performed using Cochrane Database of Systematic Reviews, ACP Journal Club, Database of Abstracts of Reviews of Effects, Cochrane Central Register of Controlled Trials, Cochrane Methodology Register, Heath Technology Assessment, NHS Economic Evaluation Database, Embase and Ovid Medline from 1995 to July 2013. To achieve the maximum sensitivity of the search strategy and identify all studies, we combined the terms "mini\*" or "thoraco\*" or "video\*" or "robot\*" or "laparoscop\*" or "endoscop\*" or "port-access" or "port access" or "partial sternotomy" or "keyhole" and "mitral\*" or "Barlow\*" as either keywords or MeSH terms. The reference lists of all retrieved articles were reviewed for further identification of potentially relevant studies. All relevant articles identified were assessed with application of the selection criteria.

#### Selection criteria

Eligible comparative studies for the present meta-analysis included those in which patients with mitral valve disease underwent surgery either through the conventional sternotomy or robotic approach. When institutions reported duplicated trials with accumulating numbers of patients or increased lengths of follow-up, only the most complete studies were included. All publications were limited to human subjects and English language. Abstracts, case studies, conference presentations, editorials and letters were excluded.

### Data extraction and critical appraisal

All data were extracted from article texts, tables and figures. When insufficient data were available from publications, corresponding authors were contacted to provide additional records. Three investigators (S. G., T. A. N., and D. C.) independently reviewed each retrieved article. Discrepancies between the reviewers were resolved by discussion and consensus. The final results were reviewed by the senior investigators (C. C. and T. D. Y.).

# Statistical analysis

Meta-analysis was performed by combining the results of reported incidences of mortality, stroke, re-operation for bleeding and durations of hospitalization, ICU stay, cross-clamp time and cardiopulmonary bypass time when comparable outcomes were available. The relative risk (RR) was used as a summary statistic and the random effects model was tested, as it was assumed there were variations between studies and the calculated ratios had a more conservative value (6).  $\chi^2$  tests were used to study heterogeneity between trials. I<sup>2</sup> statistic was used to estimate the percentage of total variation across studies, due to heterogeneity rather than chance. An I<sup>2</sup> value of greater than 50% was considered substantial heterogeneity. If there was substantial heterogeneity, the possible clinical and methodological reasons for this were explored qualitatively. All P values were two-sided. All statistical analysis was conducted with Review Manager Version 5.1.2 (Cochrane Collaboration, Software Update, Oxford, United Kingdom).

# **Results**

# Quantity and quality of trials

A total of 4,968 references were identified through the nine electronic database searches. After exclusion of duplicate or irrelevant references, 66 potentially relevant articles were retrieved for more detailed evaluation. After applying the selection criteria, six comparative studies remained for assessment. Manual search of the reference lists did not identify any additional relevant studies. A summary of the search strategy is presented in *Figure 1*. All of selected studies were retrospective observational studies, as summarized in *Table 1* (7-12). In these six studies, 1,650 patients who underwent mitral valve surgery were compared, including 960 patients who underwent the robotic approach and 690 patients who underwent the conventional sternotomy approach.

#### Patient characteristics

Four out of the six selected studies reported that all patients

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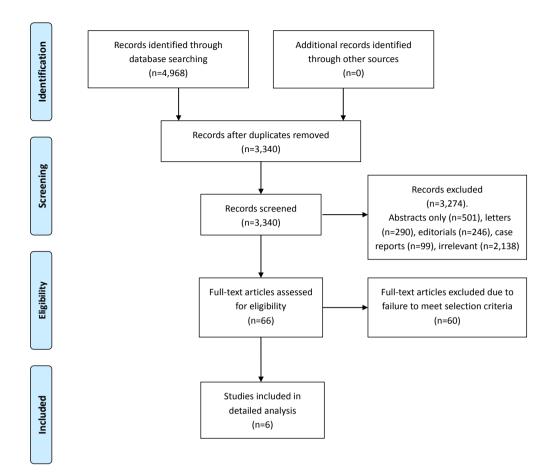


Figure 1 PRISMA chart summarizing the search strategy performed to identify relevant comparative studies on robotic vs. conventional mitral valve surgery.

Table 1 Study characteristics of relevant articles identified for meta-analysis comparing robotic vs. conventional sternotomy approaches
for patients undergoing mitral valve surgery

	0_0			Robotic	Sternotomy	Follow-up period
Author	Year	Institution	Study period	(n)	(n)	(months)
Stevens (7)	2012	East Carolina University, USA	1992-2009	447	377	77±54
Mihaljevic (8)	2011	Cleveland Clinic, USA	2006-2009	261	114	NR
Suri (9)	2011	Mayo Clinic, USA	2007-2010	95	95	NR
Kam (10)	2010	Epworth HealthCare Network, Australia	2005-2008	107	40	NR
Folliguet (11)	2006	Institut Mutualiste Montsouris, France	2000-2005	25	25	At least 24
Woo (12)	2006	University of Pennsylvania, USA	2002-2005	25	39	NR
NR, not reported						

in both the robotic and conventional groups had isolated myxomatous valve pathology (8-11). One study did not provide sufficient pathological details (12) and another study included a significant proportion of patients who had other mitral valve pathologies (7). Two retrospective studies matched patient cohorts according to prognostic factors (8,9). However, patients in the robotic group tended to be younger, with fewer incidences of diabetes and hypertension. In addition, there was a trend towards better functional status for patients included in the robotic surgical arm. A summary of these patient baseline characteristics is presented in *Tables 2,3*.

# Surgical techniques

All of the reported robotic mitral valve surgeries were performed through two or three ports and a 3-5 cm right mini-thoracotomy using the da Vinci<sup>®</sup> Surgical System (Intuitive Surgical Inc., Sunnyvale, CA, USA). Three out of the six studies reported using the endoaortic balloon occlusion device for patients who underwent robotic surgery (7,8,12). Concomitant surgical procedures such as atrial fibrillation ablation and atrial septal defect closures were reported in three studies (7-9). A summary of procedural details, including the cardioplegia strategy and repair techniques, is presented in *Table 4*.

# Assessment of primary endpoints

# Mortality

Although all six selected studies reported the incidences of all-cause perioperative mortality, only two studies reported deaths that occurred. From the available data, patients who underwent mitral surgery through the robotic approach had a significantly lower incidence of mortality compared to the conventional sternotomy approach [0.5% vs. 2.2%; RR, 0.32; 95% confidence interval (CI), 0.12-0.83; P=0.02;  $I^2$ =0%]. These results are presented in *Figure 2*.

# Stroke

Three studies reported on the incidences of perioperative stroke, and two studies recorded events. From the available data, there was no significant difference between the robotic *vs.* conventional approaches (0.8% *vs.* 2.4%; RR, 0.50; 95% CI, 0.05-4.65; P=0.54; I<sup>2</sup>=65%). These results are presented in *Figure 3*.

# Re-operation

Re-operation for bleeding was reported in all studies, and there were no significant differences between the robotic vs. conventional approaches (3.0% vs. 3.7%; RR, 0.82; 95% CI, 0.47-1.42; P=0.47; I<sup>2</sup>=0%). These results are presented in *Figure 4*.

# Assessment of secondary endpoints

Meta-analysis identified a significantly longer duration of cross-clamp time [standardized mean difference (SMD), 2.05; 95% CI, 1.23-2.87; P<0.00001; I<sup>2</sup>=94%] and cardiopulmonary bypass time (SMD, 3.03; 95% CI, 0.84-5.23; P=0.007; I<sup>2</sup>=98%) for patients who underwent robotic surgery *vs.* conventional approach. These results are presented in *Figures* 5,6, respectively. The lengths of hospitalization (SMD, -1.07; 95% CI, -2.83-0.70; P=0.24; I<sup>2</sup>=96%) and ICU stay (SMD, -1.58; 95% CI, -3.45-0.29; P=0.10; I<sup>2</sup>=97%) were not significantly different between the two approaches.

# Sensitivity analysis

Stevens *et al.* reported a number of significant differences between the baseline patient characteristics of the robotic and conventional treatment groups (7). In addition, unlike other studies included in the present meta-analysis, a significant proportion of patients had ischaemic, rheumatic, infective or functional mitral valve pathology. Hence, a sensitivity analysis was performed by excluding data from this study. By doing so, the perioperative mortality outcome was no longer statistically significant between the robotic *vs.* conventional treatment arms, as only one other study reported any incidence of deaths.

# Echocardiography outcomes

Available echocardiographic findings were categorized into predefined severities of mitral regurgitation. Preoperatively, 443/502 patients undergoing robotic surgery had severe regurgitation and 59/502 had moderate regurgitation. The respective figures were 264/297 and 33/297 for patients undergoing conventional sternotomy. Postoperatively, 4/346 patients who underwent robotic surgery had moderate regurgitation, 24/346 had mild regurgitation and 318/346 had trivial or no residual regurgitation. The corresponding figures were 4/285, 18/285 and 263/285 for patients who underwent conventional sternotomy. A summary of these echocardiographic findings before and after surgery is presented in *Figure 7A,B*.

# Discussion

Mitral valve surgery through the robotic approach enables the surgeon minimal access and 7 degrees of freedom of movement, with additional benefits of three-dimensional visualization, tremor minimization and avoidance of the fulcrum effect associated with long-shafted endoscopic instruments. Proponents of robotic mitral surgery propose that similar surgical repairs can be performed through the

Table 2 A	summary	of patient bas	seline char	acteristics in	compara	Table 2 A summary of patient baseline characteristics in comparative studies on robotic zs. conventional mitral valve surgery	robotic vs	. conventions	al mitral v	valve surgery				
Author	Age (m	Age (mean ± SD)	Male gender,	nder, n [%]	n [%] DM, n [%]	%]	HTN, n [%]	[%]	PVD, n [%]	%]	СОРD, n [%]	u [%]	Previous [%]	Previous stroke, n [%]
	Robotic	Robotic Sternotomy Robotic Ster	Robotic	Sternotomy	Robotic	notomy Robotic Sternotomy Robotic Sternotomy Robotic Sternotomy Robotic Sternotomy Robotic Sternotomy	Robotic (	Sternotomy	Robotic	Sternotomy	Robotic	Sternotomy	Robotic	Sternotomy
Stevens (7)	57±13	57±13 60±14	279 [62]	180 [48]	25 [6]	58 [15]	188 [42] 184 [49]		3 [1]*	14 [4]*	35 [8] 33 [9]	33 [9]	RN	RN
Mihaljevic (8)	56±11 61±11	61±11	204 [78]	85 [75]	5 [2]	6 [5]	102 [40] 52 [46]		29 [11] 3 [3]	3 [3]	10 [4]^ 10 [9]^	10 [9]^	3 [1]	2 [2]
Suri (9)	55±11	56±14	73 [77] 76 [80]	76 [80]	1 [1]	2 [2]	32 [34] 29 [31]	29 [31]	0	0	6 [6]	5 [5]	1 [1]	0
Kam (10)	Kam (10) 58±14 62±11	62±11	76 [71] 33 [83]	33 [83]	1 [1]	1 [3]	32 [30] 15 [38]	15 [38]	0	0	NR	NR	4 [4]	2 [5]
Folliguet (11)	59±11	60±11	16 [64] 17 [68]	17 [68]	RN	RN	RN	ШN	RN	ЯN	0	0	NR	RN
Woo (12) 60±3 60±2	60±3	60±2	17 [68] 24 [62]	24 [62]	1 [4]	3 [8]	NR	NR	3 [12] 4 [10]	4 [10]	NR	NR	4 [16] 5 [13]	5 [13]
*, patient hypertens	ts with sé sion; PVD,	, patients with severe PVD were omitted; '	rere omitt ascular dis	ed; ^, spec sease; COPE	sifically r D, chroni	*, patients with severe PVD were omitted; ^, specifically mentions COPD only. NR, not reported; SD, standard deviation; DM, diabetes mellitus; HTN, hypertension; PVD, peripheral vascular disease; COPD, chronic obstructive pulmonary disease.	PD only. pulmonar	NR, not rep y disease.	orted; S	sD, standarc	deviati	on; DM, dia	tbetes m	ellitus; HTN,

Table 3 A summary of patient baseline functional status and underlying valvular pathology	summary	r of patie	nt basel	ine fu	nctional	status ar	nd under	rlying v	alvular pa	tholog	A									
	NYHA, n [%]	l%] u							Valvular pathology, n [%]	oathol	ogy, n [%	[0								
V-HOCK	Robotic	0			Sterno	Sternotomy			Robotic					0	Sternotomy	<u>Y</u>				
	_	=	≡	≥	_	=	≡	≥	Myxo. Degen.	lsch.	Isch. Infec. Rheum. Funct. Other	heum. F	unct. O		Myxo. Degen.	lsch.	Infec.	Isch. Infec. Rheum. Funct. Other	unct. (	Other
Stevens (7) 339 [76]	7) 339 [76	[	108 [2	108 [24]	177 [47]	[21	200 [53]	3]	358 [80]	4 [1]	20 [4] 16	5 [4] 3	8 [9] 1	1 [2] 1	65 [44]	24 [6]	32 [8]	358 [80] 4 [1] 20 [4] 16 [4] 38 [9] 11 [2] 165 [44] 24 [6] 32 [8] 56 [15] 23 [6]		77 [20]
Mihaljevic 131 (8) [50]	131 [50]	97 [37]	31 [12]	2 E	37 [33]	54 [47]	22 [19]	1 [1]	261 [100]	0	0 0	0	0		114 [100] 0	0	0	0	0	-
Suri (9)	85 [89]		10 [11]	Ξ	86 [91	_	6] 6		95 [100] 0	0	0 0	0	0		95 [100] 0	0	0	0 0		0
Kam (10) NR	RN	NR	ЯN	RN	NR NR	NR	RN	NR	107 [100]	0	0 0	0	0		40 [100] 0		0	0	0	-
Folliguet (11)	17 [68]	17 [68] 6 [24] 2 [4]	2 [4]	0	16 [64	16 [64] 5 [20] 4 [16] 0	4 [16]		25 [100] 0		0	0	0		25 [100] 0	0	0	0	U	-
Woo (12)	NR	NR	NR	RN	NR NR	RN	NR	ЯN	NR	ЯN	NR NR		NR N	NR	NR	NВ	NR	NR	NR	NR
NYHA, New York Heart Association functional functional; NR, not reported.	ew York F NR, not	Heart As reporte	sociatic d.	on fun		classific	ation; n	nyxo d	classification; myxo degen, myxomatous degeneration; isch, ischaemic; infec, infective; rheum, rheumatic; funct,	komat	ous dege	eneratior	n; isch, i	ischaei	nic; infec	c, infec	tive; rhe	eum, rheu	matic; 1	unct,

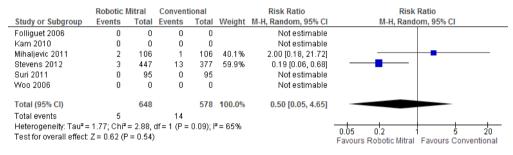
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Author	Robotic access approach	clamp technique	Robotic Sternotomy		Sternotomy	Robotic	Sternotomy	Conversion to sternotomy
Stevens (7)	3 ports & 3-4 cm incision right infra- mammary fold	Aortic cross- clamp or endoballoon	AG & RG	Isolated annuloplasty (54/442); chordal procedure (223/442); post. leaflet resection (245/442)	Isolated annuloplasty (78/208); chordal procedure (46/208); post. leaflet resection (74/208)	Leaflet sliding plasty (103/442); AF ablation (84/447)	Leaflet sliding plasty (16/208); AF ablation (22/377)	٣
Mihaljevic (	3 ports & mini- thoracotomy in 4th right ICS (mid-axillary)	Aortic cross- clamp or endoballoon	AG & RG	Annuloplasty (261/261); leaflet resection (243/261); chordal procedure (8/261); edge-to-edge (26/261)	Annuloplasty (113/114); leaflet resection (105/114); chordal procedure (5/114); edge-to-edge (4/114)	ASD/PFO closure (34/261); AF ablation (22/261)	ASD/PFO closure (7/114); AF ablation (31/114)	24/261
Suri (9)	3 ports & 4 cm incision lateral to camera port	Aortic cross-clamp	AG NR	Annuloplasty and leaflet correction	Annuloplasty and leaflet correction	ASD/PFO closure; AF ablation (MAZE procedures)	ASD/PFO closure; AF ablation (MAZE procedures)	0/95
Kam (10)	2 ports & 4 cm right thoracotomy (<4 cm)	NR	NR NR	NR	NR	NR	NR	NR
Folliguet (1 -	2 ports & 4-5 cm Folliguet (11) 5th right ICS lateral incision	Aortic cross-clamp	AG NR	Quadrangular resection; open band annuloplasty	Quadrangular resection; open band or closed ring	NR	NR	1/25 (extended thoracotomy)
Woo (12)	3 ports & 4th right ICS incision	Aortic cross- clamp or endoballoon	AG & RG	Leaflet, chordal and annular reconstruction as needed	Leaflet, chordal and Leaflet, chordal and annular reconstruction annular reconstruction NR as needed as needed	NR	NR	NR
AG, antegra	ade; RG, retrograde; NR	R, not reported	; ICS, intercostal spa	AG, antegrade; RG, retrograde; NR, not reported; ICS, intercostal space; AF, atrial fibrillation; ASD; atrial septal defect; PFO, patent foramen ovale.	SD; atrial septal defect; P	FO, patent for	ramen ovale.	

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	Robotic I	/litral	Convent	ional		Risk Ratio	Risk Ratio
Study or Subgroup	Events	Total	Events	Total	Weight	M-H, Random, 95% Cl	M-H, Random, 95% CI
Folliguet 2006	0	25	0	25		Not estimable	
Kam 2010	0	107	0	40		Not estimable	
Mihaljevic 2011	0	261	0	114		Not estimable	_
Stevens 2012	5	447	14	377	90.7%	0.30 [0.11, 0.83]	
Suri 2011	0	95	0	95		Not estimable	
Woo 2006	0	25	1	39	9.3%	0.51 [0.02, 12.12]	
Total (95% CI)		960		690	100.0%	0.32 [0.12, 0.83]	-
Total events	5		15				
Heterogeneity: Tau <sup>2</sup> =	= 0.00; Chi <sup>2</sup> :	= 0.10, •	df = 1 (P =	0.75); P	²=0%		
Test for overall effect	Z= 2.34 (P	= 0.02)					Favours Robotic Mitral Favours Conventiona

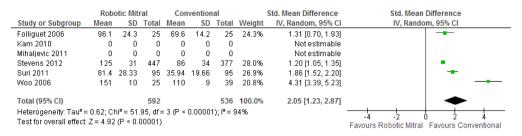
**Figure 2** Forest plot of the relative risk (RR) of perioperative mortality after robotic *vs.* conventional mitral valve surgery. The estimate of the RR of each trial corresponds to the middle of the squares, and the horizontal line shows the 95% confidence interval (CI). On each line, the numbers of events as a fraction of the total number randomized are shown for both treatment groups. For each subgroup, the sum of the statistics, along with the summary RR, is represented by the middle of the solid diamonds. A test of heterogeneity between the trials is given below the summary statistics.



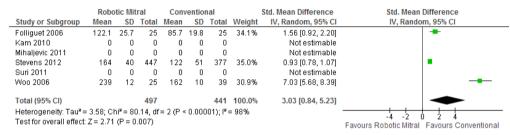
**Figure 3** Forest plot of the relative risk (RR) of perioperative stroke after robotic *vs.* conventional mitral valve surgery. The estimate of the RR of each trial corresponds to the middle of the squares, and the horizontal line shows the 95% confidence interval (CI). On each line, the numbers of events as a fraction of the total number randomized are shown for both treatment groups. For each subgroup, the sum of the statistics, along with the summary RR, is represented by the middle of the solid diamonds. A test of heterogeneity between the trials is given below the summary statistics.

	Robotic I	/litral	Convent	ional		Risk Ratio	Risk Ratio
Study or Subgroup	Events	Total	Events	Total	Weight	M-H, Random, 95% Cl	M-H, Random, 95% CI
Folliguet 2006	1	25	2	25	5.6%	0.50 [0.05, 5.17]	
Kam 2010	2	107	0	40	3.4%	1.90 [0.09, 38.70]	
Mihaljevic 2011	4	106	4	106	16.6%	1.00 [0.26, 3.89]	<b>_</b>
Stevens 2012	15	447	17	377	66.0%	0.74 [0.38, 1.47]	
Suri 2011	1	95	2	95	5.4%	0.50 [0.05, 5.42]	
Woo 2006	1	25	0	39	3.1%	4.62 [0.20, 109.04]	
Total (95% CI)		805		682	100.0%	0.82 [0.47, 1.42]	-
Total events	24		25				
Heterogeneity: Tau <sup>2</sup> =	0.00; Chi²	= 1.95, (	df = 5 (P =	0.86); P	²=0%		0.01 0.1 1 10 100
Test for overall effect:	Z = 0.72 (P	= 0.47)					0.01 0.1 1 10 100 Favours Robotic Mitral Favours Conventional

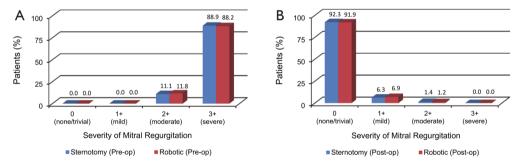
**Figure 4** Forest plot of the relative risk (RR) of re-operation for bleeding after robotic *vs.* conventional mitral valve surgery. The estimate of the RR of each trial corresponds to the middle of the squares, and the horizontal line shows the 95% confidence interval (CI). On each line, the numbers of events as a fraction of the total number randomized are shown for both treatment groups. For each subgroup, the sum of the statistics, along with the summary RR, is represented by the middle of the solid diamonds. A test of heterogeneity between the trials is given below the summary statistics.



**Figure 5** Forest plot of the standardized mean difference (SMD) of duration of cross-clamp time after robotic *vs.* conventional mitral valve surgery. The estimate of the SMD of each trial corresponds to the middle of the squares, and the horizontal line shows the 95% confidence interval (CI). A test of heterogeneity between the trials is given below the summary statistics.



**Figure 6** Forest plot of the standardized mean difference (SMD) of duration of cardiopulmonary bypass time after robotic *vs.* conventional mitral valve surgery. The estimate of the SMD of each trial corresponds to the middle of the squares, and the horizontal line shows the 95% confidence interval (CI). A test of heterogeneity between the trials is given below the summary statistics.



**Figure 7** A summary of echocardiographic findings of the severity of mitral valve regurgitation. (A) Before robotic or conventional mitral valve surgery; and (B), after robotic or conventional mitral valve surgery.

minimally invasive approach as conventional sternotomy, with potential benefits of reduced trauma and associated advantages of reduced blood product requirement and shorter hospitalization (12). Expert robotic surgeons from specialized institutions have demonstrated the feasibility of performing complicated mitral repair techniques through the robotic approach without compromising surgical outcomes (7). Recently, Nifong *et al.* reported excellent results in a group of 540 patients who underwent robotic mitral valve repairs including concomitant biatrial cryoablation procedure (13).

To systematically evaluate the outcomes of robotic *vs.* conventional mitral surgery, the present metaanalysis identified all comparative studies in the existing literature and found that robotic mitral valve surgery was associated with a statistically significant survival benefit over conventional surgery. Perioperatively, there were no significant differences in regards to the incidences of stroke or re-operation for bleeding. Cross-clamp and cardiopulmonary bypass times were significantly longer for robotic surgery, but the durations of hospitalization and ICU stay were not statistically different between the two surgical techniques.

A number of limitations to our study should be acknowledged and the results should be interpreted with caution. Firstly, our systematic review of the current literature has demonstrated that the quantity and quality of the existing evidence for robotic vs. conventional surgery is very limited. All six studies included in the meta-analysis were retrospective case-series reports with differences between the robotic and conventional patient cohorts. Without randomization, surgical outcomes may reflect the patient characteristics rather than the surgical intervention. However, attempts were made in two studies to match patients according to propensity scores to minimize selection bias (8,9). The large study by Stevens et al. reported a heterogenous cohort of patients with various mitral valve pathologies and unbalanced patient baseline characteristics. When data from this study was excluded from analysis, the mortality difference between the two surgical techniques was no longer significant. Secondly, as with any novel surgical or medical intervention, there is the possibility for publication bias, with potentially more favorable outcomes being reported from large volume expert centers that may not be representative of all institutions. Finally, significant heterogeneity was detected for the analysis of stroke and secondary outcomes such as crossclamp time, cardiopulmonary bypass duration and length of hospitalization. This may reflect the limited number of studies and different surgical techniques and clinical practices, respectively.

In conclusion, the present meta-analysis identified a statistical survival benefit for robotic mitral valve surgery vs. the conventional sternotomy approach. However, this was largely a reflection of the heterogenous patient cohort between the two treatment arms within the identified retrospective studies. Without randomization and adequate patient matching, the existing evidence for robotic surgery is not robust, and limited conclusions can be drawn from the current literature. However, it has been demonstrated that robotic mitral valve surgery can be feasibly performed by expert surgeons for selected patients. These centers have recognized that a successful robotic surgical program is dependent on the development of a highly specialized and well-trained team including anesthesiologists, perfusionists, operating room staff, and surgeons (14). In addition, they believe that surgical units must be able to maintain a sufficient volume of referrals to attain and maintain safety. As there is currently limited robust clinical data on the surgical outcomes of robotic mitral valve surgery, this novel

procedure should be limited to specialized centers that fulfil the above criteria. Ultimately, surgical outcomes of mitral valve surgery will be dependent on choosing the right procedure by the right surgeon for the right patient, rather than by the length of the skin incision (15).

# Acknowledgements

Disclosure: The authors declare no conflict of interest.

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